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Measurement and Feedback

ITER Operational Considerations

ITER-Specific Challenges

Measurement and Feedback

Vertical Position Measurement Magnetometry and reflectometry

Vertical Velocity Measurement Saddle-loops and pickup loops

Active Stability Feedback VS1 and VS2 circuits plus proposed VS3

Passive Stability Feedback

Vacuum vessel and conducting blanket support structure

Vertical Position Measurement

Magnetic field measurements41 full flux loops, 36 internal and 5 externalRogowski coils for halo currentsExternal hall effect sensors $60 B_{Tan}$ and $60 B_{Norm}$ 100s of inductive probes for B_{Tan} and B_{Norm}

Used for...

Equilibrium reconstruction Vacuum flux and driven coil currents

Position reconstruction from reflectometry Reflectometry limited for probing in H-mode Pedestal too steep for typical resolution Can watch position of fixed density point at edge Pedestal acts as stable plasma 'wall'



Vertical Velocity Measurement

Saddle loopsArea-measurements of \dot{B}_{Norm} More than 120 in-vessel saddle loopsUsually integrated to get B_{Norm} ,but \dot{B}_{Norm} can indiciate plasma movement



Pickup coils Analogous to guitar pickups Point-measurements of \dot{B} $B = \mu n I \Rightarrow \dot{B} = \mu n \dot{I} = \frac{\mu n V}{L}$



Active Stability Feedback Systems VS1 Circuit: PF2-5 outboard poloidal coils Superconducting NbTi coils 2/3 of PF: total ~40 MA-turns Dicharge time constant ~14s

VS2 Circuit: CS2U & CS2L central solenoid coils Superconducting Nb₃Sn coils 1/3 of CS: total ~45 MA-turns Discharge time constant ~7.5s

VS3(?): New (proposed?) in-vessel VS coils Standard copper coils



Passive Stability Feedback Systems

Stainless steel vacuum vessel wall As well as suppressing ripple, enhances stability Together with blanket supports, $R_t \approx 7.7 \mu \Omega$

Toroidally continuous conducting blanket supports Improve up/down symmetry for plasma position Reduce displacement after disturbance by ~50%

Vacuum vessel vertical displacement characteristics Vertical displacement VV mode time constant ~0.25s Typical initial displacement after MD ~10-20mm Vertical instability growth time ~60-160ms





from Gribov (2007)

ITER Operational Considerations

Operational Parameters l_i, κ

Operational Control Limits $m_s, \Delta Z_{max}$

Feedback Control Figures of Merit $\Delta \tilde{Z}_a$ and $\Delta \tilde{Z}_n$

Operational Parameters: l_i and κ In a circular plasma, $l_i(3) = \frac{2\int B_{\theta}^2 dV}{R(\mu_0 I_p)^2}$ Normalized for ITER's plasma shaping, $l_i(1) = \left[\left(\frac{\mu_0 I_p}{\int dl_{\theta}} \right)^2 2\pi R \int dA_{\phi} \right] \frac{2\int B_{\theta}^2 dV}{R(\mu_0 I_p)^2}$ However, most analysis simply uses $l_i(3)$

It can be shown that $l_i(3) \leq \left[\frac{1}{2} + \ln(q_{95})\right] \frac{2\kappa_a}{1+\kappa^2}$ to 1st order for a "top-hat" current

 l_i should be *smaller* in ITER

Operational Control Limits: m_{s}

Stability margin as function of l_i , κ , q_{95}

 l_i will be smaller in ITER Higher m_s for a given κ q_{95} much lower in ITER

Suggests overall lower m_s in ITER operating regime



However: m_s is not necessarily a good cross-machine figure of merit! More useful when normalized against $m_s(\min)$ of machine's coils, structure, PS, etc. Seems to be found *empirically* for each machine ITER expected to have $m_s/m_s(\min) \sim 2$, comparable to DIII-D and C-Mod

Marginally

trajectory

controllable

Controllable

trajectories

0.6

displacement

0.8

1.0

displacement

Example of Analysis and Gedanken Experiment to Calculate ΔZ_{max} Operational Control Limits: ΔZ_{max} Vertical Displacement Sweep w/PS 0.4 Uncontrollable Defined by $\Delta Z_{max} \approx -\frac{\partial z}{\partial I_s} v_z u_z L_{*s}^{-1} \vec{b}_c \frac{V_{sat}}{\gamma_z} e^{-\gamma_z T_{PS}}$ displacements 0.3 $\Delta Z_{max} = 0.04$ Coil geometry effects from $\frac{\partial z}{\partial I}$ and u_z E 0.2 $l_i = 1.2, \gamma_z = 10.7 \text{ rad/s}$ 0. *Implications*: $\Delta Z_{max} \propto \gamma_z^{-1}$ for a slow power supply 0.2 0.4 Maximum^{0.0} For a very fast power supply, ΔZ_{max} becomes Time (s) controllable displacement mostly independent of growth rate from Humphreys (2009) $\Delta \mathbf{Z}_{max} = 0.04 \text{ m}$ With ΔI_{max} , if $\Delta I_{max} L_c \gamma_z / V_{sat} < 1$, $\Delta Z_{max} \propto \Delta I_{max}$ $\Delta Z_{max} \propto V_{sat}$ Individual coil set effectiveness scales like $\frac{\partial z}{\partial I} v_z u_z L_{*s}^{-1} \vec{b}_c$ *For Example:*

Using only VS1, $\Delta Z_{max} \sim 4$ cm ITER rampup

Figures of Merit: $\Delta \tilde{Z}_a$ and $\Delta \tilde{Z}_n$ $\Delta \tilde{Z}_{a} \equiv \frac{\Delta Z_{max}}{a} \qquad \Delta \tilde{Z}_{n} \equiv \frac{\Delta Z_{max}}{\langle \Delta Z_{max} \rangle}$ Many machines see $\langle \Delta Z_{noise} \rangle_{rms} \sim 0.01 a$, suggesting $\Delta \tilde{Z}_a$ is a good enough measure $\Delta \tilde{Z}_{a} < 2\%$ represents high risk of VDEs $2\% < \Delta \tilde{Z}_a < 4\%$ characterizes marginal control $\Delta \tilde{Z}_{a} > 5\%$ stable in C-Mod and DIII-D In ITER, using only VS1 (aka PF2-5), $\Delta \tilde{Z}_a \sim 2\%$ Even using VS1 + VS2 (PF2-5, CS2U, CS2L), $\Delta \tilde{Z}_a \sim 4\%$





from Humphreys (2009)

Specific Challenges

H-Mode implies ELMs ELM-induced difficulties Solutions

ITER Scaling Challenges of ITER's size Solutions

Specific Challenges and Solutions

Edge Localized ModesCharacteristically associated with H-modeELMs can displace the plasma verticallyELMs can also falsify plasma ΔZ Moves pedestal position relative to bulk plasmaGenerates extra B_{norm} noiseEffectively decreases $\Delta \tilde{Z}_n$

Work on JET indicates illusory ∆Z from ELMs may be suppressed with careful tuning of gain on magnetic sensors
ELM control methods may reduce magnitude of noise
Pellet injection
Jogging

Specific Challenges and Solutions

ITER Scaling Issues Stable $\Delta \tilde{Z}_a > 5\%$ region of means $\Delta Z_{max} > 10$ cm (!) VS1 + VS2 (PF2-5, CS2U, CS2L): $\Delta \tilde{Z}_a \sim 4\%$ NSTX study: machine properties can *reduce* effective $\Delta Z_{max} \sim 20\%$ Nonaxisymmetries of passive components? Nonlinear effects from plasma-limiter interactions? Other unidentified effects? Vertical instability growth times as short as 60ms

Proposal (approved?) to include in-vessel VS3 coils Ongoing study should clarify effects of asymmetries and nonlinearities Vacuum vessel design should minimize asymmetry effects (e.g. ripple) dz/dt of current centroid monitored at 1kHz

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